

Final User Ces Workshop

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System overview and what is new in version 2.0

Presenters:

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Members of the consortium available to answer your questions

Université catholique de Louvain



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System evolution (before version 2.0)





BETA version

Only available for the PAs

Version 1.0 release candidate

Open-source

Possibility for the PAs to access a test machine with the system

Version 1.1

1st consolidated version

Big evolutions:

- Corrections in the advanced processors
- Sen2Cor L2A compatible
- Move of the system database to a docker container

=> 2 Q&A sessions

organized end of June

Version 1.2

Mainly corrections, adaptations and improvements based on project and user's experience

Version 1.3

Mainly corrections, adaptations and improvements based on project and user's experience

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Version 2.0 released at the end of January 2021





Version 2.0

Big evolutions:

- Markers database
- Tillage processor
- Dockerization
- · ...

- Added
 - Markers database (dedicated session)
 - Tillage processor (dedicated session)
 - Docker containers for Sen4CAP components (processors, utilities, SNAP 8, orchestrator if needed)
 - Support for MAJA 4.2.1
 - **New DEM integration** (ASTER DEM and EU DEM) for European Northern countries
- Changed
 - DBus replaced with a HTTP communication interface
- Fixed
 - Some **database concurrency corrections** for the L2A launcher script

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Sen4CAP system : simple parametrization and subsidy application upload



Before the monitoring period

Monitoring period

System initialization

Start of the season

End of the season...



Upload

Sen4CAP system : main parameters settings			
Area of Interest	Shapefile to be uploaded		
Monitoring period	Start and end dates to be defined		
S1+S2 / S1+S2+L8	L8 to be selected		

Sen4CAP system : data from PA

1. Subsidy application



2. Tables and config files



data Subsidv Subsidy application layer (shapefile) application (shp) **Tables and** config files (csv)

L4A crop code LUT L4B config file L4C config file + agri practices tables

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Sen4CAP system





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• Sentinel-1 & Sentinel-2

- Object-based
- Markers DB
- User-friendly with web interface
- Open source
- Automated
- Modular

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- Demonstrated at national scale
- NRT or off-line
 production
- Locally or in the cloud

Sen4CAP system – S1/S2/L8 ingestion and preprocessing





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Automated import / download of the low-level satellite data



- Query of the list of low-level products corresponding to the site and monitoring period done on ESA SciHub (Copernicus Open Access Hub) => with any configuration
- If a local root is defined in the data sources configuration, direct link / symbolic link to the low-level products corresponding to the list (or copy) (+ automatic download in the case of missing products)
- **Otherwise**, **download** of the low-level products corresponding to the list **from ESA SciHub** (Copernicus Open Access Hub)

Automatic

European Space Agency

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Sentinel-2 pre-processing (from S2 Level-1C)



- **Correcting** single-date Level-1C products from the **effects of the atmosphere** that reduce the quality of the images
- Level-2A products are systematically generated at the ground segment over Europe since March 2018 using Sen2COR processor
- Sen4CAP reads L2A Sen2COR products, but also proposes MAJA as alternative L2A preprocessing module



https://earth.esa.int/web/sentinel/user-guides/sentinel-2-msi/product-types/level-2a

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Sentinel-1 pre-processing (from S1 SLC Interferometric Wide images)



• **SAR backscattering** (after calibration, sigma nought σ 0)

The **SAR backscattering** is a measure of the **outgoing radar signal that the target redirects directly back towards the radar antenna**. It is a measure of the reflective strength of a target. The normalised measure of the radar return from a distributed target is called the backscatter coefficient, or **sigma nought** (σ_0), and is defined as per unit area on the ground. In general, due to the high dynamic of the SAR backscatter coefficient, **the amplitude** = sqrt(σ_0) is preferred for visualization purposes.

SAR coherence

The coherence, which assume values in the range [0.0, 1.0], gives an **estimation of changes in the scene taking into account variation of the phase of the backscattered radar signal:** high coherence (close to 1.0) implies that the scene is steady (e.g. urban areas, bare soil, rocks and so on), low coherence indicates changes between the two acquisition dates.

The coherence is **calculated from a couple of SAR images acquired from the same** orbit (in order to have significant coherence values the images must be acquired with similar sight of view). The high revisit time of Sentinel-1 mission allows to calculate **short term coherence** from couples of images acquired one **6 days** from the other.

https://earth.esa.int/handbooks/asar/CNTR5-2.html

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Sen4CAP system – Biophysical indicators (L3B)



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Biophysical indicators – LAI, FAPAR, FCover retrieval using BV-Net approach + NDVI

Growing vegetation indicators



4 indicators about the evolution of the green vegetation corresponding to the vegetative development of the crop



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Sen4CAP system – Markers database





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Markers Database – Overview





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Sen4CAP system – Crop type mapping (L4A)



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Crop type mapping (L4A) – Fine-tuned Random Forest classification

Crop type mapping



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Crop type mapping (L4A) – results

Crop type mapping

- **Results of the classification**: the 2 first predictions with the highest confidence levels + the confidence levels
- Results of the conformity assessment at the parcel level
- Results of the crop diversification assessment at the holding level



CT_decl	CT_pred_1	CT_conf_1	CT_pred_2	CT_conf_2	CTnumDIV_p	Classif_r	CD_cat	CD_diagn
56	56	0.88500	58	0.04500	56	Classified_conf	Category1	Compliant
56	56	0.68900	58	0.19100	56	Classified_conf	Category1	Compliant
49	49	0.54000	55	0.13800	49	Classified_conf	Category1	Compliant
10	10	0.99200	11	0.00800	10	Classified_conf	Category1	Compliant
3000	3000	0.93700	802	0.03000	299	Classified_conf	Exemption1	Not_required
3000	3000	0.90900	802	0.02400	299	Classified_conf	Exemption1	Not_required
3000	3000	0.81600	802	0.08900	299	Classified_conf	Exemption1	Not_required
NULL	NULL		NULL		NULL	Not_classified	Exemption1	Not_required
3000	3000	0.96800	802	0.01600	299	Classified_conf	Exemption1	Not_required
3000	3000	0.87800	802	0.03300	299	Classified_conf	Exemption1	Not_required
3000	3000	0.69100	707	0.06700	299	Classified_conf	Exemption1	Not_required
2000	2000	0.01500	240	0.03700	200	0.00	n (* 1	N

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Crop type mapping (L4A) – automatic validation

Crop type mapping





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Sen4CAP system – Grassland mowing detection (L4B)





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Grassland mowing detection (L4B) - S1 & S2 time series analysis

Grassland mowing detection



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Grassland mowing detection (L4B) - results

Grassland mowing detection

- **Results of the L4B grassland** • mowing detection with:
- ⇒ **Number** of detected mowing events

m1_dend

1 2020-07-04 10:3... 2020-07-14 10:3... 0.825000000000... S2

2 2020-05-18 10:3... 2020-06-02 10:3... 0.875000000000... S2/S1

2 2020-06-10 18:0... 2020-06-16 18:0... 0.23800000000... S1

2 2020-06-03 18:0... 2020-06-09 18:0... 0.394000000000... S1

1 2020-07-22 10:3... 2020-07-27 10:3... 0.833000000000... S2/S1

0

0

0

0

- **Date** of each detected mowing event
- Conformity regarding the rules

m1_conf

0.00000000000... 0

0.00000000000... 0

0.00000000000... 0

0.00000000000... 0

m1_mis

0

0

0

0

and				
ng				
wing				
e rule	es		ł	
m2_dstart	m2_dend	m2_conf	m2_mis	m3_dst
0	0	0.00000000000	0	0
0	0	0.00000000000	0	0
0	0	0.00000000000	0	0
0	0	0.00000000000	0	0
2020-06-27 10:3	2020-07-05 10:3	0.82500000000	S2	0
0	0	0.00000000000	0	0
2020-08-21 10:3	2020-08-26 10:3	0.777000000000	S2	0
2020-07-22 10:3	2020-07-27 10:3	0.82000000000	S2	0
0	0	0.00000000000	0	0

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m1_dstart

mow_n

0 0

0 0

0 0

0 0

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Sen4CAP system – EFA practices monitoring (L4C)



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EFA practices monitoring (L4C) - from Sentinel-1 and Sentinel-2 markers analysis

Agricultural practices monitoring (EFA)



• Analysing the dense S1 and S2/L8 time series per parcel



- Generation of weekly PRACTICE markers
- 4 monitored practices: harvest, catch crop, nitrogen fixing crop and fallow land
- + TILLAGE DETECTION

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Applying decision trees to determine the degree of compliancy of the declared agricultural practice (defined with the PAs)

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http://esa-sen4cap.org/content/technical-documents

EFA practices monitoring (L4C) - markers

Agricultural practices monitoring (EFA)

• Related to vegetation state or vegetation change on a parcel

MARKERS FOR HARVEST				
M1	M1: Presence of vegetation in the main vegetation season (pre-requisite)	High values of NDVI		
M2	M2: Loss of vegetation	Break in NDVI (decrease)		
M3	Loss of vegetation	Break in backscatter ratio (increase)		
M4	Low/no vegetation	High values of backscatter ratio		
M5	Low/no vegetation (stable conditions)	Break in VV Coherence (increase) or high values of VV Coherence		
MARKERS FOR DECLARED PRATICES				
M6	Presence of vegetation	High values of NDVI		
M7	Growth of vegetation	Break in NDVI (increase)		
M8	No loss of vegetation	No break in NDVI (decrease)		
M9	No loss of vegetation	No increase of the backscatter ratio		
M10	Presence of vegetation (dynamic conditions)	No Break in VV Coherence (increase) and no high values of VV Coherence		

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EFA practices monitoring (L4C) - Monitoring of harvest/clearance of a parcel with winter wheat + catch crop (NLD)



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Thank you for your attention and your contribution



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